Phase Transformation

1.Diffusional

Require movement of atoms by a diffusion process driven by a chemical potential gradient
 a.Nucleation and growth
 b.Spinodal decomposition

2. Displacive (Non-diffusional)

- Involve cooperative movement of atoms in a shearing action during phase transformation
- e.g., Martensitic transformation in steel
- Stability condition with respect to infinitesimal fluctuation







- No energy barrier for decomposition
- Kinetics controlling process
- Spinodal decomposition

(b) Metastable region



-Small fluctuation, $C \rightarrow A+B$, and $G_C < G_F$, energetically unfavorable -Large fluctuation, $C \rightarrow A+D$ and $G_C > G_E$, energetically favorable -Nucleation and growth



Fig. 5.42 A coarsened spinodal microstructure in Al-22.5 at% Zn-0.1 at% Mg solution treated 2 h at 400 °C and aged 20 h at 100 °C. Thin foil electron micrograph (× 314 000). (After K.B. Rundman, *Metals Handbook*, 8th edn., Vol. 8, American Society for Metals, 1973, p. 184.)

Spinodal decomposition of $V_{0.7}Ti_{0.3}O_2$ annealed at 450°C for 7 days in N_2 Bright field image



Wavelength of spinodal \approx 22 nm



Dark field image







RY Tsai, 2017

Spinodal Decomposition

Composition fluctuation $C_o \Rightarrow C_o + \delta C$ and $C_o - \delta C$ $G_{C_o+\delta C} = G_{C_o} + (\pm \delta C)G'_{C_o} + 1/2(\pm \delta C)^2 G''_{C_o}$ $G'_{C_o} = (\frac{\partial G}{\partial C})_{C_o}, \ G''_{C_o} = (\frac{\partial G^2}{\partial^2 C})_{C_o}$

The change in Gibbs free energy accompanying the composition fluctuation

 $\Delta G = G_{C_o + \delta C} - G_{C_o} \qquad \Delta G = \frac{1}{2} (\delta C)^2 G_{C_o}^{"}] \qquad \Delta G = \frac{1}{2} (\delta C)^2 G_{C_o}^{"}] \qquad G_{C_o}^{"} < 0$ $+ \frac{1}{2} [(-\delta C)G_{C_o}^{'} + \frac{1}{2}(-\delta C)^2 G_{C_o}^{"}] \qquad G_{C_o}^{"} < 0$ $= \frac{1}{2} (\delta C)^2 G_{C_o}^{"} \qquad G_{C_o}^{"} > 0$ $G_{C_o}^{"} < 0 \Rightarrow \Delta G < 0 \Rightarrow unstable$ $G_{C_o}^{"} > 0 \Rightarrow \Delta G > 0 \Rightarrow stable$



$$C(x,t) = \frac{4C_0}{\pi} \sum_{j=0}^{\infty} \frac{1}{(2j+1)} \sin(\frac{(2j+1)\pi x}{h}) \exp(-(\frac{(2j+1)\pi}{h})^2 Dt)$$

$$C(x,0) = \frac{4C_0}{\pi} \sum_{j=0}^{\infty} \frac{1}{(2j+1)} \sin(\frac{(2j+1)\pi x}{h})$$

$$C(x,t) = C(x,0) \exp(-(\frac{(2j+1)\pi}{h})^2 Dt)$$
Amplification Factor (AF) = exp(-($\frac{(2j+1)\pi}{h}$)² Dt)
(1)D < 0 $\Rightarrow \frac{d(AF)}{dt} > 0 \Rightarrow$ Spinodal Decomposition
(2)D > 0 $\Rightarrow \frac{d(AF)}{dt} < 0 \Rightarrow$ Homogenization
 $C_0 = C_0 = C$



Regular Solution

$$\Delta H_{m} \neq 0 \quad \& \quad \Delta S_{m}^{exc} = 0$$

(Ideal Solution $\Delta H_{m} = 0 \quad \& \quad \Delta S_{m}^{exc} = 0$)
$$\Delta H_{m} = \Omega X_{A} X_{B} \text{ where } \Omega = N_{o} Z \varepsilon \text{ and}$$
$$\varepsilon = \frac{1}{2} (\varepsilon_{AA} + \varepsilon_{BB}) - \varepsilon_{AB}, \quad \varepsilon_{XX} > 0$$

$$\Delta S_{m} = -R (X_{A} \ln X_{A} + X_{B} \ln X_{B})$$
$$\Delta G_{m} = \Delta H_{m} - T \Delta S_{m}$$
$$= \Omega X_{A} X_{B} + RT (X_{A} \ln X_{A} + X_{B} \ln X_{B})$$

Regular Solution

$$\Delta H_m = P_{AB}(1/2(\varepsilon_{AA} + \varepsilon_{BB}) - \varepsilon_{AB}) = P_{AB}\varepsilon$$

 $P_{AB}=((1/2)ZN_{o})(2X_{A}X_{B})$ =ZN_{o}X_{A}X_{B} : Probability to form A-B bonds

$$\Delta H_{m} = ZN_{o}X_{A}X_{B} \varepsilon = ZN_{o} \varepsilon X_{A}X_{B} = \Omega X_{A}X_{B}$$

$$\begin{split} \Omega = \mathsf{ZN}_{o} \varepsilon \\ \Omega < \mathbf{0} &\rightarrow \text{ attraction between unlike ions} \\ &\rightarrow 1/2(\varepsilon_{AA} + \varepsilon_{BB}) < \varepsilon_{AB} \\ \Omega > \mathbf{0} &\rightarrow \text{ repulsion between unlike ions} \\ &\rightarrow 1/2(\varepsilon_{AA} + \varepsilon_{BB}) > \varepsilon_{AB} \end{split}$$

For Ideal Solution $1/2(\varepsilon_{AA} + \varepsilon_{BB}) = \varepsilon_{AB}$ $\varepsilon = 0 \rightarrow \Omega = 0 \rightarrow \Delta H_m = 0$





Regular Solution

$$\frac{\partial \Delta G_m}{\partial X_B} = RT(-\ln X_A + \ln X_B) + \Omega(1 - 2X_B)$$
$$\frac{\partial^2 \Delta G_m}{\partial X_B^2} = RT(\frac{1}{X_A} + \frac{1}{X_B}) - 2\Omega$$
$$\frac{\partial^3 \Delta G_m}{\partial X_B^3} = RT(\frac{1}{X_A^2} - \frac{1}{X_B^2})$$

Spinodal line is determined where

 $\frac{\partial^2 \Delta G_m}{\partial X_B^2} = 0 \Longrightarrow X_A X_B = \frac{RT}{2\Omega}, \quad (X_A + X_B = 1)$ $\Rightarrow \text{ Spinodal parabola}$

Critical point is determined where

$$\frac{\partial \Delta G_{m}}{\partial X_{B}} = 0$$

$$\frac{\partial^{2} \Delta G_{m}}{\partial X_{B}^{2}} = 0$$

$$\frac{\partial^{3} \Delta G_{m}}{\partial X_{B}^{3}} = 0 \rightarrow 2$$

 $T_{c} = \frac{2X_{B}^{c}(1 - X_{B}^{c})\Omega}{R}$ $T_{c} > 0 \rightarrow \Omega \text{ must be positive}$

 X_B^C is such that T_C is the maximum decomposition temperature associated with the miscibility gap $\rightarrow X_A = X_B = 0.5$

$$\rightarrow \mathsf{T}_{\mathsf{C}} = \frac{\mathsf{\Omega}}{\mathsf{2}\mathsf{R}}, \ \mathsf{\Omega} \uparrow \mathsf{T}_{\mathsf{C}} \uparrow$$



Nucleation



Nucleation and Growth





Phase Transformation in Pb-Sn Alloy System





Surface Tension & Energy

The surface stays under a tension or a stress (force per unit length, or work per unit area) which is called surface





Diagram not to scale

Unbalanced forces for the molecules at the surface yield an excess free energy which is called Surface Energy

$$dG = -SdT + VdP + \gamma dA$$

$$\Rightarrow \gamma = (\frac{\partial G}{\partial A})_{T,P}$$

The free energy of a system containing an interface of area A and excess free energy per unit area (surface energy: γ) is given by

Х

 $G=G_{\circ}+\gamma A$ where G_{\circ} is the bulk free energy. $dG=\gamma dA+Ad\gamma$ For a liquid film suspended by a wire frame, which is moved by a force of F W(work)=FdxSurface tension $(\gamma_{T})=$ Force/unit length = F/L Then W = $\gamma_{T}Ldx = \gamma_{T}dA$ (work done on the system)=dG $\gamma_{T}dA = \gamma dA+Ad\gamma$ $\gamma_{T} = \gamma + A \frac{d\gamma}{dA}$

For liquid: Since the surface is unable to support shear stresses, the atoms within the liquid can rearrange during the stretching process and thereby maintaining a constant surface structure and energy; i.e., $d\gamma/dA=0 \rightarrow \gamma_T=\gamma$ For solid: Since the atoms take much longer to move from the bulk to surface, the surface structure and energy will be changed when it is under stress. If this time is long in relative to the time of the experiment then $d\gamma/dA\neq 0 \rightarrow \gamma_T \neq \gamma$. At temperatures near the melting point, however, $\gamma_T=\gamma$ because the mobility of atoms is fast enough to restore surface structure.

Broken-bond Model for surface energy



Average Surface Energies

Metals	T _m (°C)	γ _{SV} (mJm ⁻²)	
Sn	232	680	
Al	660	1080	
Ag	961	1120	
Au	1063	1390	
Cu	1084	1720	
δ -Fe	1536	2080	
Pt	1769	2280	
W	3407	2650	

 $H_2O: 72 \text{ mJm}^{-2}$



At the interface of solid/liquid, the inter-atomic bonds become gradually weakened, which increases the disorder. At equilibrium (e.g., T_M), the high enthalpy of liquid is balanced by a high entropy so that both phases have the same free energy. In the interface, however, the balance is disturbed thereby resulting in an excess free energy of $\gamma_{\rm SL}$.

$$G_v^L = H_v^L - TS_v^L$$

 $G_v^S = H_v^S - TS_v^S$



Experimentally measured solid/liquid interfacial free energy

Metals	T _m (°C)	$\gamma_{\sf SL}$ (mJm ⁻²)	
Sn	232	54	
Pb	327	33	
Al	660	93	
Ag	961	126	
Au	1063	132	
Cu	1084	177	
Mn	1220	206	
Ni	1452	255	
Со	1490	234	
Fe	1536	204	
Pd	1555 209		
Pt	1769	240	

Effect of Curvature



Work of expansion on the gas (\triangle PdV) =the reduction in surface energy (γ dA) γ dA= \triangle PdV $\Rightarrow \triangle$ P= γ dA/dV dV=4 π r²dr, dA=8 π rdr \triangle P= γ (8 π rdr)/4 π r2dr =2 γ /r (Young-LaPlace Eq.)

 $\Delta \textbf{P}$ for water droplets of different radii

Radius (μ m)	1000	100	1	0.01
$\triangle P$ (atm)	0.0014	0.0144	1.44	144



Stability of Droplet

Effects of Curvature

At constant T $dG = V_A^M dP$ V_A^M :molar volume of species A $\Delta G_A = G_A(P) - G_A^o(P_o) = G_A(r) - G_A^o(\infty)$ $= \int_{P_o}^P V_A^M dP = V_A^M(P - P_o)$ $= V_A^M \Delta P = V_A^M(\frac{2\gamma}{r})$

$$\mu_{\rm A}({\rm r}) - \mu_{\rm A}^{\rm o}(\infty) = \frac{2\gamma V_{\rm A}^{\rm M}}{r}$$

 $\mu_{\mathrm{A}}^{\mathrm{o}}(\infty)$: Chemical potential under a flat surface

- $\boldsymbol{\cdot}$ Chemical potential increasing with decreasing particle size
- Smaller particles exhibiting higher solubility.

Ostwald Ripening (Coarsening): Larger particles grow at the expense of smaller particles







Precipitation from Homogeneous Solutions (PFHS)

 $A + B \leftrightarrow X(s) + Y$



Effect of Curvature



Effects of Curvature on Solubility of Particles









Homogeneous Nucleation



- g^{I} and g^{v} : free energy per atom in the bulk phases

e. g., Supersaturated Vapor \rightarrow Liquid (V \rightarrow L)

 $dG = -SdT + VdP + \gamma dA + \Sigma \mu_i dn_i$

Assumption: A small liquid droplet has thermodynamic

properties similar to bulk liquid



$$= \frac{4\pi r_{\text{liquid}}^3}{3} \Delta G_{\text{V}} + 4\pi r_{\text{liquid}}^2 \gamma_{\text{LV}}$$

V:volume

Assuming that the liquid droplets are spherical and isotropic

$$\Delta G_{r} = \frac{4\pi r^{3}}{3V_{l}} (g^{l} - g^{v}) + 4\pi r^{2} \gamma_{LV}$$
$$= n(g^{l} - g^{v}) + \eta n^{2/3} \gamma_{LV}$$



where V₁: volume per atom in the liquid state, r: the radius of liquid droplet, n: number of atoms in the liquid droplet, and $\eta = (36\pi)^{\frac{1}{3}} (V_l)^{\frac{2}{3}}$

$$\frac{\partial \Delta G_r}{\partial r} = 0 = \frac{4\pi r^2}{V_l} (g^l - g^v) + 8\pi r \gamma_{LV}$$

$$r_c = (-) \frac{2\gamma_{LV} V_l}{g^l - g^v}$$
(2)

Replacing eq. (2) into eq. (1)

$$\Delta G_{C} = \frac{16\pi\gamma_{LV}^{3}V_{l}^{2}}{3(g^{l} - g^{v})^{2}}$$
(3)

Replacing eq. (2) into eq. (3)

$$\Delta G_C = \frac{4\pi r^2 \boldsymbol{\gamma}_{LV}}{3} = \frac{1}{3} (4\pi r^2 \boldsymbol{\gamma}_{LV})$$

Critical free energy =1/3(total surface energy)

$$\Delta G = VdP = g^{l} - g^{v}$$
ideal gas: $V = \frac{RT}{P}$







Freezing

 $L \rightarrow S$

Freezing or Solidification

$$r_{c} = \frac{-2\gamma_{LS}}{\Delta G_{v}} = \frac{-2\gamma_{LS}}{\Delta H_{M}\Delta T/T_{M}}$$
$$\Delta G_{c} = \frac{16\pi\gamma_{LS}^{3}}{3(\Delta G_{v})^{2}} = \frac{16\pi\gamma_{LS}^{3}}{3(\Delta H_{M}\Delta T/T_{M})^{2}}$$

$$\Delta G_{\mathcal{C}} = \frac{1}{3} \Big(4 \pi r_{\mathcal{C}}^2 \gamma_{LS} \Big)$$

As $T = T_M$, $\Delta T = 0$, then $r_c \longrightarrow \infty$ and $\Delta G_c \longrightarrow \infty$, barrier for nucleation is infinite at T_M , implying that supercooling is needed for Homogeneous Nucleation. For example, a liquid nickel can be supercooled by 250K below T_M (1453°C) without solidification, or pure water can be supercooled to as low as -42°C without being frozen into ice.
Effect of Undercooling







Undercooling (Δ T) Required for Homogeneous Nucleation

Size Distribution of Nuclei

$$\frac{n_r}{n_0} = \exp(-\frac{\Delta G_r}{RT})$$

n₀: number of clusters having atomic radius n_r : number of clusters having radius of r ΔG_r : formation free energy of clusters with a radius of r



Clusters having a radius of r





Undercooling $\triangle T=10K$

Too low concentration \rightarrow Homogeneous nucleation does not take place



	∆ T (K)	r _c (nm)	∆ G (J)	n(r _c) (cm ⁻³)	
	10	35.00	1.3x10 ⁻¹⁵	10-24000	r_{max} (n _r =1 cm ⁻³)
	100	3.50	1.3x10 ⁻¹⁷	10 ⁻²⁸³	
	300	1.17	1.4×10 ⁻¹⁸	7×10 ⁻¹⁰	ଧୁ ଅନ୍ୟୁ ଅନ୍ୟୁ ଅନୁ ଅନୁ ଅନୁ ଅନୁ ଅନୁ ଅନୁ ଅନୁ ଅନୁ ଅନୁ ଅନ
	325	1.07	1.2x10 ⁻¹⁸	1.4×10 ⁻⁵	T ^m T ^m
	340	1.03	1.1×10 ⁻¹⁸	2.8×10 ⁻³	dus V
<					
	400	0.90	8.2×10 ⁻¹⁹	3.7×10 ³	

$$\Delta T=340-400K r_c = \frac{-2 \gamma_{LS}}{\Delta H_M \Delta T} \frac{1}{\overline{V}}$$

Undercooling required for homogeneous nucleation

 $\mathbf{r}_{C} > \mathbf{r}_{max} \rightarrow \mathbf{N}_{O}$ homogeneous nucleation $\mathbf{r}_{\mathcal{C}} = \mathbf{r}_{\max} \rightarrow \Delta \mathbf{T}_{\min}$ for homogeneous nucleation $r_c < r_{max} \rightarrow$ homogeneous nucleation Temperature T_M T_{N} r_c=r_{max} $r_{max} (n_r = 1 \text{ cm}^{-3})$ Homogeneous Nucleation for Ni $\Delta T_N = 345 - 350K$ $\Delta T_{observed} = 319K$



Homogeneous Nucleation Rate $I = q_0 O_c Z_c$

- I = nucleation rate
- q_o = jump frequency
- O_c = area of critical nucleus
- Z_c = number of critical nucleus

Volmer Theory

Assumptions (1) Bimolecular process

$$Q_1 + Q_1 \to Q_2$$
$$Q_2 + Q_1 \to Q_3$$
$$\dots$$
$$Q_n + Q_1 \to Q_{n+1}$$

(2) Neglect the reverse reaction between embryos (irreversible process) Note: If reversible process is considered, I=0

$$\therefore I = q_n O_n Z_n - q_{n+1} O_{n+1} Z_{n+1}$$

Since $Z_n = Z_{n+1}$ (equilibrium distribution), I = 0.

(3) Equilibrium embryo size distribution



$$N_n = Nexp(-\frac{\Delta G_n}{RT})$$

the statistical distribution function for embryos containing n atoms

N: number of atoms in the vapor phase

 ΔG_n : the standard free energy change resulting from the conversion of vapor into embryos

$$n < n_c \quad Z_n = N_n = Nexp(-\frac{\Delta G_n}{RT})$$

$$n = n_c$$
 $Z_c = Nexp(-\frac{\Delta G_c}{RT})$

- I: nucleation rate (sec⁻¹)
- q_o: probability per unit time per unit area of capturing one vapor atom
- O_c : area of critical nucleus
- Z_{c} : number of critical nucleus

(4) N_{C+1} is removed from the assembly

$$\Delta G_{c} = \frac{16\pi \gamma^{3} (V_{l})^{2}}{3(g^{l} - g^{v})^{2}} = \frac{16\pi \gamma^{3} (V_{l})^{2}}{3(kT)^{2} [ln(i)]^{2}}$$

$$i = \frac{P}{P_{e}} : \text{supersaturation}$$

$$j = i - 1 = \frac{P - P_{e}}{P_{e}} : \text{degree of supersaturation}$$

$$j = i - 1 \approx \ln(i)$$

$$\therefore \Delta G = V dP = g^{l} - g^{v}$$

$$i deal \ gas \Rightarrow V = \frac{kT}{P}$$

$$g^{l} - g^{v} = -kT \ln \frac{P}{P_{e}} = -\frac{2\gamma V_{l}}{r}$$

$$\therefore I = \frac{\alpha P}{\sqrt{2\pi M kT}} O_{c} \text{Nexp} (-\frac{16\pi \gamma^{3} (v_{l})^{2}}{3(kT)^{3} [ln(i)]^{2}}$$

$$I$$

Becker-Doring Theory

Assumptions

- (1) Bimolecular process
- (2) Reverse reaction considered



(The number of embryos at a given size should remain effectively constant although embryos might grow or shrink in size (the probability for either direction is equal)

$$\begin{array}{ll} n \to 0 & Z_n \to N_n \\ n \to \infty & Z_n \to 0 \end{array}$$

$$\mathbf{I} = \mathbf{q}_0 \mathbf{O}_c \cdot \left(\frac{\Delta \mathbf{G}_c}{3\pi \mathbf{k} \mathbf{T}}\right)^{\frac{1}{2}} \mathbf{N}_c^{-1} \cdot \mathbf{Nexp}\left(-\frac{\Delta \mathbf{G}_c}{\mathbf{k} \mathbf{T}}\right)$$

$$q_0 = \frac{\alpha P}{\sqrt{2\pi MkT}}$$

 O_{C} = area of critical nucleus

Liquid -> Solid: Nucleation of solid from liquid

- Kinetic theory of gaseous collision is no longer applicable
- q_0 replaced by diffusion in liquid

$$q_{0} = \Gamma = \upsilon \exp\left(-\frac{\Delta g_{n}}{kT}\right) \qquad \Delta G$$

$$= \frac{kT}{h} \exp\left(-\frac{\Delta g_{n}}{kT}\right)$$

$$I = \frac{NkT}{h} \left(\frac{O_{C}}{N_{C}}\right) \left(\frac{\Delta G_{C}}{3\pi kT}\right)^{\frac{1}{2}} \exp\left(-\frac{\Delta G_{C} + \Delta g_{n}}{kT}\right)$$

$$\left(\frac{O_{C}}{N_{C}}\right) \left(\frac{\Delta G_{C}}{3\pi kT}\right)^{\frac{1}{2}} \approx 10^{1} \sim 10^{2}$$

$$\therefore I = \frac{NkT}{h} \exp\left(-\frac{\Delta G_{C} + \Delta g_{n}}{kT}\right)$$

$$^{V}I = \left(\frac{N}{V}\right) \left(\frac{kT}{h}\right) \exp\left(-\frac{\Delta G_{C} + \Delta g_{n}}{kT}\right)$$

$$\frac{N}{V} \approx 10^{22} - 10^{23} \ cm^{-3}$$

$$\frac{kT}{h} = 10^{13} \ \sec^{-1}$$

$$\exp\left(-\frac{\Delta g_{n}}{kT}\right) \approx 10^{-2} \ for \quad L \to S$$

$$\Delta g_{n} \sim 10 \ \text{kJ/mol in liquid metals}$$



$$\omega = \upsilon \exp\left(-\frac{\Delta G_m}{R T}\right)$$
$$\Gamma = \mathbf{Z} \omega \mathbf{P}_{\mathbf{v}}$$

$$V_{I} \approx 10^{33} \exp\left(-\frac{\Delta G_{C}}{kT}\right)$$
Note: $\frac{kT}{h} = v$, $D = a_{0}^{2}v$

$$D = P_{v}wa_{o}^{2}$$

$$V_{I} \approx N \cdot \frac{D}{a_{0}^{2}} \exp\left(-\frac{\Delta G_{C}}{kT}\right)$$

$$D \approx 10^{-5} \frac{cm^{2}}{sec}, a_{0}^{2} \approx 10^{-16} cm^{2}, N \approx 10^{22} cm^{-3}$$

$$V_{I} = 10^{33} \exp\left(-\frac{\Delta G_{C}}{kT}\right)$$

For solidification

$$\Delta G_C = \frac{4\eta^3 \gamma^3}{27(\Delta G_v)^2} = \frac{4\eta^3 \gamma^3}{27(\frac{\Delta H_m \Delta T}{T_m})^2}$$

$$\therefore \Delta G_{v} = \frac{\Delta H_{m} \Delta T}{T_{m}}$$

$$\therefore {}^{V}I \cong 10^{33} \exp\left[-\frac{4\eta^{3} \gamma^{3} (T_{m})^{2}}{27kT (\Delta H_{m})^{2} (\Delta T)^{2}}\right]$$

Homogeneous Nucleation



Liquid→Solid



$$\Delta \mathcal{G}_{c} = \frac{4}{27} \frac{\eta^{3} \gamma^{3}}{(g^{s} - g')^{2}}$$
$$\Delta \mathcal{G}_{v} = g^{s} - g' = \frac{\Delta \mathcal{H}_{m} \Delta T}{T_{m}}$$



Mobility term: $\frac{\Delta g_n}{kT}$ Formation term: $\frac{A}{kT(\Delta T)^2}$ -ln(^vI) $\alpha \frac{\Delta g_n}{kT} + \frac{A}{kT(\Delta T)^2}$



Phase Transformation in Solids e.g., $\alpha \Leftrightarrow \beta$

The total interfacial energy ($\gamma_{\text{interface}}$) is the sum of surface energy contributed by chemical bonding at interface (γ_{Ch}) and the strain energy (γ_{St}).

$$\gamma_{\text{interface}} = \gamma_{Ch} + \gamma_{St} = 4\pi r^2 \gamma_{\alpha\beta} + \frac{4\pi}{3} r^3 \cdot c\varepsilon^2$$

where c is the elastic constant and ε is the relative strain due to lattice mismatch.



Coherent Interface



$$\gamma_{\text{interface}} = \gamma_{Ch} \alpha \left(\frac{dX}{dx}\right)^2$$
$$\approx 0 - 200 \text{ mJ/m}^2$$
$$dX$$

 $\frac{dx}{dx}$: concentration gradient

$$\varepsilon \approx \frac{\left|a_{\alpha} - a_{\beta}\right|}{a_{\alpha}} \approx \frac{\left|a_{\alpha} - a_{\beta}\right|}{a_{\beta}} \le 1\%$$

 $\gamma_{\text{interface}} = \gamma_{Ch} + \gamma_{St} \approx 0 - 200 \text{ mJ/m}^2$

Gibbs free energy of an atom in a concentration gradient is not the same as the Gibbs free energy of that atom in a solution of uniform concentration

$$\gamma = \kappa (\frac{dX}{dx})^2$$

Interfacial free energy is proportional to (composition gradient)² **Regular Solution**

(1) In a uniform solution
$$\Delta H_m = \Omega X_A X_B = \Omega X_A (1 - X_A)$$
$$\Omega = Z[E_{AB} - \frac{1}{2}(E_{AA} + E_{BB})] = Z \cdot \Delta E$$
$$\Delta H_m = Z X_A (1 - X_A) \cdot \Delta E = 12C(1 - C) \cdot \Delta E \quad (Z=12)$$
(2) With a concentration analient

(2) with a concentration gradient



 $\Delta H_m = 6C_o(1-C_o)\Delta E$ $+3[(C_{o}+\Delta C)(1-(C_{o}+\Delta C))]\Delta E$ $+3[(C_o - \Delta C)(1 - (C_o - \Delta C))]\Delta E$ $= 12C_o(1-C_o)\Delta E + 6(\Delta C)^2\Delta E$ $=12C_o(1-C_o)\Delta E + 6(\frac{dC}{dx})^2(\Delta x)^2\Delta E$ Uniform concentration Excess Gibbs free

energy resulted from a non-uniform concentration

Semicoherent Interface



$$\varepsilon \approx \frac{\left|a_{\alpha} - a_{\beta}\right|}{a_{\alpha}} \approx \frac{\left|a_{\alpha} - a_{\beta}\right|}{a_{\beta}} \le 25\%$$

$$\gamma_{\text{interface}} = \gamma_{Ch} + \gamma_{St} \approx 200 - 500 \text{ mJ/m}^2$$

Incoherent Interface



$$\varepsilon \approx \frac{\left|a_{\alpha} - a_{\beta}\right|}{a_{\alpha}} \approx \frac{\left|a_{\alpha} - a_{\beta}\right|}{a_{\beta}} > 25\%$$

$$\gamma_{\text{interface}} = \gamma_{Ch} + \gamma_{St} \approx 500 - 1000 \text{ mJ/m}^2$$

Effects of interface nature on Nucleation and Growth

For very small particles (though still larger than r_c), the term of strain energy is smaller than the surface energy (chemical contribution), and total interfacial energy is small (due to the limited surface area, and thus the limited number of interface chemical bonding), thereby it is energetically favorable to maintain coherent.

Diffusion normally occurs by a vacancy mechanism in substitutional solid solutions. In the case of the formation of a precipitate, a reconstruction of the lattice occurs, where involves the *creation and annihilation of vacancies*, if the interface is semicoherent or incoherent. However, if the interface is coherent, no such vacancies processes involved. The concentration profile across precipitate/matrix interface for the three different interfaces are shown below:



Boundary migration mobility (M) M (coherent) < M (semicoherent) < M (incoherent)

Precipitates on Grain Boundary



FIGURE 3.45

Possible morphologies for grain-boundary precipitates. Incoherent interfaces smoothly curved: coherent or semicoherent interfaces planar.



FIGURE 3.46

An α precipitate at a grain boundary triple point in an α - β Cu–In alloy. Interfaces A and B are incoherent, value C is semicoherent (×310). (After Chadwick, G.A., *Metallography of Phase Transformations*, Butterworths, London, 1972.)

Homogeneous Nucleation in Solids Effects of Strain Energy (ΔG_s)





Heterogeneous Nucleation





Heterogeneous Nucleation



Nucleation of CO_2 bubbles around a finger

Heterogeneous Nucleation

-Impurities or strained regions of lattice enable nuclei to be formed with a much smaller free energy of activation than that of homogeneous nucleation

- • α phase in contact with a solid phase of S, and β phase formed at the interface -Assuming $\sigma_{\alpha\beta}$ is isotropic -The volume of embryo = $\eta^{\beta}r^{3}$ and the
- surface area of contact with the α phase = $\eta^{\alpha\beta}r^{2}$, where η^{β} and $\eta^{\alpha\beta}$ are shape factors. $\sigma_{\alpha\beta}$



-The free energy of formation is

$$\Delta G^{s} = \frac{\eta^{\beta} r^{3}}{V^{\beta}} (g^{\beta} - g^{\alpha}) + r^{2} (\eta^{\alpha\beta} \gamma^{\alpha\beta} + \eta^{\alpha s} (\gamma^{\beta s} - \gamma^{\alpha s}))^{\alpha s}$$
$$\frac{\partial \Delta G^{s}}{\partial r} = 0 \Rightarrow r_{c} \text{ and } \Delta G^{s}_{c}$$
$$\Delta G^{s}_{c} = \frac{4}{27} \frac{[(\eta^{\alpha\beta} \gamma^{\alpha\beta} + \eta^{\alpha s} (\gamma^{\beta s} - \gamma^{\alpha s})]^{3} (V^{\beta})^{2}}{(\eta^{\beta})^{2} (g^{\alpha} - g^{\beta})^{2}}$$

From the geometry of the figure

$$\eta^{\beta} = \pi (2 - 3\cos\theta + \cos^{3}\theta)/3$$
$$\eta^{\alpha\beta} = 2\pi (1 - \cos\theta)$$
$$\eta^{\alpha s} = \pi \sin^{2}\theta$$

$$\Delta \mathcal{G}^{her} = V_{s} \Delta \mathcal{G}_{v} + \mathcal{A}_{sL} \gamma_{sL} + \mathcal{A}_{sM} \gamma_{sM} - \mathcal{A}_{sM} \gamma_{ML}$$

$$\mathcal{A}_{sL} = 2\pi r^{2} (1 - \cos \theta)$$

$$\mathcal{A}_{sM} = \pi r^{2} \sin^{2} \theta$$

$$V_{s} = \frac{\pi r^{3} (2 + \cos \theta) (1 - \cos \theta)^{2}}{3}$$

Heterogeneous Nucleation



Contact Angle



Liquid drop on solid surface. The condition $\theta < 90^{\circ}$ indicates that the solid is wet by the liquid, and $\theta > 90^{\circ}$ indicates non-wetting, with the limits $\theta = 0$ and $\theta = 180^{\circ}$ defining complete wetting and complete non-wetting, respectively



Nucleation of Melting



$$\gamma_{SV} = \gamma_{LS} + \gamma_{LV} \cos \theta \quad (\theta: \text{contact angle})$$
$$\Rightarrow \cos \theta = \frac{\gamma_{SV} - \gamma_{LS}}{\gamma_{LV}}$$
$$\gamma_{SV} >> \gamma_{LS} + \gamma_{LV} \Rightarrow \theta = 0$$

No superheating required for nucleation of liquid during melting

$$I = q_0 O_C N^S \exp(-\frac{\Delta G_c^S}{kT})$$
$$q_0 = \frac{\alpha P}{\sqrt{2\pi M kT}} \quad for \quad V \to L, \quad V \to S$$
$$I = (\frac{kT}{h}) N^S \exp(-\frac{\Delta G_c^S + \Delta g_n}{kT}) \quad for \quad L \to S, \quad S \to S$$

Note: The key difference between heterogeneous and homogeneous nucleation rates

1. N v.s. N⁵ 2. $\Delta G_c v.s. \Delta G_c^s$ $\frac{\Delta G_c^{S}(\text{hetero})}{\Delta G_c(\text{homo})} = \frac{2 - 3\cos\theta + \cos^3\theta}{4}$ $\theta > 0 \qquad \frac{\Delta G_c^s(hetero)}{\Delta G_c(homo)} > 0$ $\theta = \frac{1}{2}\pi \qquad \frac{\Delta G_c^s(hetero)}{\Delta G_c(homo)} = \frac{1}{2}$ $\theta = 0$ $\frac{\Delta G_c^S(hetero)}{\Delta G_c(homo)} = 0$ $\theta = \pi$ $\frac{\Delta G_c^s(hetero)}{\Delta G_c(homo)} = 1$




Growth (without composition change)

e.g., Crystal growth

I.Normal growth (continuous growth)

- Wilson-Frenkel model
- Every site is a growth site, or there is a constant number of growth sites
- Number of growth sites \neq f (T)
- Rough interface on atomic scale (micro- roughness)



Velocity of interface approximated by wave equation

$$u = \lambda \Gamma_{net}$$

= $\lambda v_0 \exp(-\frac{\Delta G_a}{kT})[1 - \exp(-\frac{V\Delta G_V}{kT})]$
= $\lambda \Gamma_{LS}[1 - \exp(-\frac{V\Delta G_V}{kT})]$

(1) For small under-cooling ($\Delta T \rightarrow 0$ and ΔG_v is small)



$$1 - \exp(-\frac{V\Delta G_V}{kT}) \approx 1 - (1 - \frac{V\Delta G_V}{kT})$$
$$= \frac{V\Delta G_V}{kT}$$

Growth rate is proportional to under-cooling when ΔT is small

(2) For large under-cooling $\rightarrow |V \Delta G_v| >> kT$

$$u = \lambda v_0 \exp(-\frac{\Delta G_a}{kT}) = \frac{D}{\lambda} \quad (D = \Gamma \lambda^2)$$







FIGURE 3.22

Two-dimensional cells of a soap solution illustrating the process of grain growth. Numbers are time in minutes. (After Smith, C.S., *Metal Interfaces*, American Society for Metals, Cleveland, 1952, 81.)



Grain Growth

The arrows indicate the directions in which grain boundaries migrate.





Grain Growth



II. Lateral Growth



(1) Spiral Growth

- Interface is smooth on atomic scale, but imperfect
- Growth takes place only at the dislocation ledges; the fraction of preferred growth sites on the interface in growth from the melt is approximately by



 $f \approx \frac{\Delta T}{2\pi T_F}$ (Hilling & Turnbull, J. Chem. Phys. 24, 914 (1956))



$$u = f v a_0 [1 - \exp(-\frac{V \Delta G_V}{kT})]$$

*Small ΔT , $u \alpha (\Delta T)^2$

*Large ΔT , model invalid

(2) Surface Nucleation



(a)



- Growth takes place at step sites provided by two-dimension nuclei formed on the interface

 $u = Av \exp(-\frac{C}{T\Delta T})$

where A and C are constants depending on specific models.





Note: Nucleation is required on smooth surfaces, but not for rough or imperfect surfaces

Faceted dendritic growth in tertiary butyl alcohol $\triangle S/R=3$

21.18 Encets



Faceted growth in benzil $\Delta S/R=6$



igure 21.8 Snow flakes. (From Bentley and Humphreys [7]).



Figure 6.9 Polyethylene single crystal showing spiral growth [After Allen Sharples, "Introduction to Polymer Crystallization," London: Edward Arnold, Ltd., (1966)].

Jackson model of a crystal interface

Ref: K.H. Jackson, "Mechanism of Growth", in Liquids, Metals, and Solidification, ASM, Cleveland, 1958, p174-186.

-Thermodynamic Approach: similar to regular solution



 $\frac{\Delta G_{s}}{Nk_{\rho}T_{F}} = \alpha\theta(1-\theta) + \theta \ln\theta + (1-\theta)\ln(1-\theta)$ where $\theta = \frac{N_A}{N_A}$ $\frac{\Delta G_s}{Nk_{\rho}T_{\rho}} = \alpha \frac{N_{A}}{N^2} (N - N_{A}) - \ln(\frac{N}{N - N_{\rho}}) - \frac{N_{A}}{N} \ln(\frac{N - N_{A}}{N}) \quad (*)$ $\frac{\Delta G_{\rm s}}{Nk_{\rm B}T_{\rm E}}$: the normalized free energy change per atom added to surface N: the total number of surface sites $N_{A:}$ the number of occupied surface sites $\alpha = (\frac{\Delta S_f}{k_p}) f_k = (\frac{\Delta H_f}{k_p T_p}) f_k$

 $\Delta\, H_{f}:$ Latent heat of transformation

f_k: Crystallographic factor

-Fraction of all nearest neighbors lying in the plane parallel to the face under construction, e.g., (111) in FCC: 6 bonds out of 12 in plane, $f_k=0.5$.

In other words, α depends upon (1) Crystallographic factor (f_k) (2) Thermodynamic factor ($\Delta H_f/T_e$) which can be used to predict "roughness of surface".



- Little anisotropy in growth rate
- Normal growth \rightarrow non-faceting
- -Micro-roughness \rightarrow macro-smoothness
- -Diffusion-controlling process mostly



$$\frac{\Delta G_s}{Nk_g T_E} = \alpha \theta (1 - \theta) + \theta \ln \theta + (1 - \theta) \ln (1 - \theta)$$

$$\frac{d' (\frac{\Delta G_s}{Nk_g T_E})}{d \theta} = 0 = \alpha (1 - 2\theta) + \ln \theta - \ln (1 - \theta)$$
or $\frac{\theta}{1 - \theta} = \exp[-\alpha (1 - 2\theta)]$
For large α , the minimum is located at
 $\theta \approx \exp(-\alpha) \Rightarrow micro - smoothness$
For small α , the minimum is located at
 $\theta = \frac{1}{2} \Rightarrow micro - roughness$

$$\frac{d^2 (\frac{\Delta G_s}{Nk_g T_E})}{d \theta^2} = -2\alpha + \frac{1}{\theta} + \frac{1}{1 - \theta}$$

$$= -2\alpha + 4, \quad \text{for } \theta = \frac{1}{2}$$
So the critical value of α is $\alpha_c = 2$
The free energy has two minima for $\alpha > 2$,
and only one, at $\theta = \frac{1}{2}$ for $\alpha < 2$.

α>2

- -The lowest free energy occurs when there are new extra atoms on the plane and a few atoms missing from the plane below. This is a "smooth" surface.
- Surface nucleation required
- Growth rate \rightarrow anisotropy \rightarrow faceting
- Macro-roughness \rightarrow micro-smoothness
- Interface-controlling process mostly

Low α



Micro-roughness Macro-smoothness Non-faceting



High α

Micro-smoothness Macro-roughness Faceting



$$\begin{split} \frac{\Delta H_f}{RT_E} < 2 & - \text{Most metals in solid-liquid transformation} \\ - \text{Inorganic glass formers such as} \\ & \text{SiO}_2 (\alpha = 0.6) \text{ and } \text{GeO}_2 (\alpha = 1.3) \\ \hline \frac{\Delta H_f}{RT_E} > 2 & - \text{Most organics on solidification} \\ - \text{Multi-component inorganic} \\ & \text{glass/metallic oxide systems} \\ & Na_2O \cdot 2SiO_2 (\alpha = 4) \\ & PbO \cdot 2B_2O_3 (\alpha = 30) \\ & \text{Tri-}\alpha - \text{naphthylbenzene} (\alpha = 10.7) \\ \hline \frac{\Delta H_f}{RT_E} \approx 2 & - \text{Semimetals} \\ & Ga (\alpha = 2.2), Bi(\alpha = 2.4) \\ - \text{Elementary semiconductors} \\ & Si (\alpha = 3.24), Ge(\alpha = 3.0), H_2O(\alpha = 2.63) \end{split}$$

e.g., (111) faces of Si and Ge

$$f_k = \frac{3}{4}, \quad \alpha > 2$$

- -For small $\Delta \mathsf{T},$ both grow with large flat surface
 - →faceting
- -At large $\triangle T$ (30K for Ge and 90K for Si) flat surface disappears \rightarrow roughness in the form of dendrites.







 Δ S/R=7.46

Nonfaceted and faceted interfaces. (a) Crystals of Cu₃P in the eutectic matrix showing nonfaceted interfaces in the Cu-10.5%P alloy.

 $500 \times$ (b) Faceted interface of salol.¹⁰ (c) Faceted cuboids of the compound, β '-SnSb in Sn-rich

matrix.¹⁰ $100 \times [After G.A.$ Chadwick, "Metallography of Phase Transformation," New York: Crane, Russak and Co., (1972)].











 $\Delta S_f = \frac{\Delta H_f}{T_E}$: entropy change on crystallization

Metals from the melt1Si, Ge, Sb, Ga from the melt3Many organic compounds6Metals from the vapor10Complex molecules20Polymers>100

Homogeneous Nucleation in Solids with Composition Change





$$\begin{array}{c} \mathsf{T}_{e} \rightarrow \mathsf{T}_{2} \\ \alpha \rightarrow \alpha + \beta \end{array}$$

Composition change

 $\mathsf{X}_{\mathsf{o}} \rightarrow \mathsf{X}_{\mathsf{e}} + \mathsf{X}^{\beta} \; (\boldsymbol{\Delta} \mathsf{X} = \mathsf{X}_{\mathsf{o}} - \mathsf{X}_{\mathsf{e}})$

Total free energy change: ΔG_{o}

To nucleate β in α phase, however, the composition does not change significantly $X_{\alpha} \approx X_{\alpha}^{\alpha}$

Free energy change: ΔG_n (nucleation)

At point P: per mole of β removed from α phase

 $\Delta G_P = X^{\beta}_A \mu^{\alpha}_A + X^{\beta}_B \mu^{\alpha}_B$

At Point Q: per mole of β formed $\Delta G_Q = X_A^{\beta} \mu_A^{\beta} + X_B^{\beta} \mu_B^{\beta}$

 $\Delta G_n = \Delta G_P - \Delta G_Q = X_A^\beta (\mu_A^\alpha - \mu_A^\beta) + X_B^\beta (\mu_B^\alpha - \mu_B^\beta)$

:Driving force for nucleation

Effects of Interfacial Strain Energy on Homogeneous Nucleation in Solids



Effects of Alloy Composition on Nucleation Rate



Effects of Undercooling on Heterogeneous Nucleation Rate



Growth Kinetics with Composition Change



Diffusion Controlling Growth with Composition Change



Diffusion Controlling Growth with Composition Change

The same area (Accumulation = Depletion)





$$(X_{\beta} - X_{o}) \cdot x = (X_{o} - X_{e}) \cdot \frac{L}{2} = \Delta X_{o}$$

$$v = \frac{dx}{dt} = \frac{D \frac{dX}{dx}}{(X_{\beta} - X_{e})} = \frac{D \frac{\Delta X_{o}}{L}}{(X_{\beta} - X_{e})}$$

$$\therefore \frac{dX}{dx} \approx \frac{\Delta X_{o}}{L}$$

$$\therefore L = \frac{2(X_{\beta} - X_{o}) \cdot x}{\Delta X_{o}}$$

$$v = \frac{dx}{dt} = \frac{D(\Delta X_{o})^{2}}{2(X_{\beta} - X_{e})(X_{\beta} - X_{o}) \cdot x}$$

$$x = \frac{\Delta X_{o}}{[(X_{\beta} - X_{e})(X_{\beta} - X_{o})]^{1/2}} \sqrt{Dt}$$

X : molar fractionx : thickness of precipitate



Reaction Controlling Growth Kinetics with Composition Change





Age Hardening of Al-Cu Alloys



Isothermal Kinetics of Transformation by Nucleation and Growth

1.J. W. Christian, p15-22, (1975).

2.Johnson and Mehl, Trans. AIME, <u>135</u>, 416 (1939)

3.Avrami, J. Chem. Phys., 7, 1103 (1939); Avrami, J. Chem. Phys., 8, 212 (1940);

Avrami, J. Chem. Phys., <u>9</u>, 177 (1941)

4.Burke and Turnbull, Prog. In Metal Phys., <u>3</u>, 220 (1952)

Goal: Develop kinetic equations for volume fraction transformed (X vs. t)

In a homogeneous reaction, the volume transforming in a short time interval is proportional to the volume remaining untransformed at the beginning of this interval, and this leads to a first order rate reaction process.

For a reaction
$$\alpha \rightarrow \beta$$

$$\frac{dV^{\beta}}{dt} = k(V - V^{\beta})$$

$$\frac{V^{\beta}}{V} = 1 - \exp(-kt) = X \quad (Volume \ fraction \ transformed)$$

where V is the total volume, V^{β} is the transformed volume and k is the rate constant.



Formal Theory of Transformation Kinetics



- Randomness of active nucleation sites
- VI (Nucleation Rate) = number of nuclei
 - formed per unit volume of α per unit time
- Number of particles formed between τ and τ +d τ = Vad τ where τ is an incubation time.
- Volume of each β particle formed is

 $t < \tau, V_{\tau}^{\beta} = 0$ $t > \tau, V_{\tau}^{\beta} = \frac{4\pi}{3} [u(t-\tau)]^{3}$

assuming that u is constant in time, which is true for the system without composition change.

At early stage of transformation, $V^{\beta} \ll V^{\alpha}$ and impingement can be ignored, and volume of β phase increases as

$$dV^{\beta} = V_{\tau}^{\beta} \bigvee I V^{\alpha} d\tau$$

$$V^{\beta} = \frac{4\pi}{3} V \int_{0=\tau}^{t=\tau} \bigvee I u^{3} (t-\tau)^{3} dt$$

$$V^{\beta} = V^{\alpha} + V^{\beta}$$

$$V^{\beta} = V^{\alpha} + V^{\beta}$$

$$V^{\beta} = V^{\beta} \bigvee I V^{\alpha} d\tau$$

$$V^{\beta} = V^{\alpha} + V^{\beta}$$

$$V^{\beta} = V^{\beta} \bigvee I V^{\alpha} d\tau$$

$$V^{\beta} = V^{\alpha} + V^{\beta}$$

$$V^{\beta} = V^{\beta} \bigvee I V^{\alpha} d\tau$$

$$V^{\beta} = V^{\alpha} + V^{\beta}$$

Assuming that VI and u are constants

$$X = \frac{V^{\beta}}{V} = \frac{\pi}{3}^{\vee} \operatorname{Iu}^{3} t^{4}$$

 $\mathbf{V}^{\beta} \boldsymbol{\langle} \boldsymbol{\langle} \mathbf{V}^{\alpha}, \mathbf{V} \approx \mathbf{V}^{\alpha}$ at early stage of transformation

 $V^{eta}_{ au}$: Volume of each eta particle



Mutual interference or impingement need to be considered at later stage of transformation. In this case, there are $^{\mathbf{V}\mathbf{V}_{\alpha}\mathbf{d}} \tau$ newly transformed regions nucleated in the α area, and $^{\mathbf{V}\mathbf{V}_{\beta}\mathbf{d}} \tau$ newly transformed regions nucleated in the β area, and Arvami called $^{\mathbf{V}\mathbf{V}_{\beta}\mathbf{d}} \tau$ as phantom nuclei and defined an "extended volume" of transformed material V_{e}^{β}

 $dV_{e}^{\beta} = (^{\vee}IV^{\beta}d\tau + ^{\vee}IV^{\alpha}d\tau)V_{\tau}^{\beta}$ $= (V^{\alpha} + V^{\beta})(^{\vee}Id\tau)V_{\tau}^{\beta}$ $= (V)(^{\vee}Id\tau)(\frac{4\pi}{3}[u(t-\tau)]^{3})$ $V_{e}^{\beta} = \frac{4\pi}{3}V\int_{0}^{t} ^{\vee}Iu^{3}(t-\tau)^{3}dt$

V_e^β differs from the actual volume of transformed materials:
 (1) it counts phantom regions, nucleated in already transformed area
 (2) treating all regions as though they continue growing irrespective of other regions

$$dV^{\beta} = (1 - \frac{V^{\beta}}{V})dV_{e}^{\beta}$$

fraction of increment due to transformation occurring in α phase

$$V_{e}^{\beta} = -V \ln(1 - \frac{V^{\beta}}{V})$$

Substituting into $V_{e}^{\beta} = \frac{4\pi}{3}V_{0}^{\dagger} V_{0}^{\dagger} U^{3}(t-\tau)^{3}d\tau$
 $\ln(1-X) = -\frac{4\pi}{3}u^{3}\int_{0}^{t} VI(t-\tau)^{3}d\tau$
 $X = 1 - \exp(-\frac{\pi u^{3} VIt^{4}}{3})$
(assuming VI and *u* are constants)
Early stage of transformation (t \rightarrow 0)
 $X = \frac{\pi}{3}^{V}Iu^{3}t^{4}$

Note: In general, ${}^{v}I$ is not constant, but may either increase or decrease with time. Avrami assumed that nucleation rate was not fixed

^vI = f(t)
^vN = ^vN₀ exp(-
$$\upsilon$$
t)
^vI(t) = $-\frac{d^{v}N}{dt} = {}^{v}N_{0}\upsilon \exp(-\upsilon t) = {}^{v}N\upsilon$
ln(1-X) = $\frac{4\pi}{3}u^{3}\int_{0}^{t}v I(t-\tau)^{3}d\tau$
= $\frac{4\pi}{3}u^{3}\int_{0}^{t}v N_{0}\upsilon \exp(-\upsilon t)(t-\tau)^{3}d\tau$
Integrating by parts gives

$$X = 1 - \exp\left[\left(\frac{-8\pi^{\nu}N_0u^3}{\nu^3}\right)\left\{\exp(-\nu t) - 1 + \nu t - \frac{\nu^2 t^2}{2} + \frac{\nu^3 t^3}{6}\right\}\right]$$

Two limiting cases

(1) ν t is small, implying that 'I is constant

$$e^{-\upsilon t} = 1 - \upsilon t + \frac{\upsilon^2 t^2}{2} - \frac{\upsilon^3 t^3}{6} + \frac{\upsilon^4 t^4}{24} - \frac{\upsilon^5 t^5}{120} + \dots$$

Eq (**) becomes $\frac{\upsilon^4 t^4}{24}$
 $X = 1 - \exp[(\frac{-8\pi^{\nu}N_0u^3}{\upsilon^3} \cdot \frac{\upsilon^4 t^4}{24})]$
 $= 1 - \exp[\frac{-\pi^{\nu}N_0\upsilon u^3 t^4}{3}]$
 $= 1 - \exp[\frac{-\pi^{\nu}N_0\upsilon u^3 t^4}{3}]$
 $= 1 - \exp[\frac{-\pi^{\nu}Iu^3 t^4}{3}]$

(**)

 \rightarrow the same as that of constant 'I and u.

(2) ν t is large, indicating that 'I goes to zero quickly. All nucleation centers will be exhausted at early stage of the transformation

Eq (**) becomes
$$\frac{\upsilon^3 t^3}{6}$$

Note: $\exp(-\upsilon t) - 1 + \upsilon t - \frac{\upsilon^2 t^2}{2} + \frac{\upsilon^3 t^3}{6} \approx \frac{\upsilon^3 t^3}{6}$ ($\exp(-\upsilon t) = 0$ when υ is large)

$$X = 1 - \exp\left[\left(\frac{-8\pi^{v}N_{0}u^{3}}{\nu^{3}} \cdot \frac{\nu^{3}t^{3}}{6}\right)\right]$$
$$= 1 - \exp\left[\frac{-4\pi^{v}N_{0}u^{3}t^{3}}{3}\right]$$

3-Dimension, spherical ^vI=0, and u is constant, n=3 in X=1-exp(-ktⁿ)

 \rightarrow Nucleation is rapid, and X is controlled by growth.

Avrami proposed that a 3-D nucleation and growth process, the equation of transformation kinetics is

 $X = 1 - \exp(-kt^n)$ (*) or $X = 1 - \exp(-(kt)^n)$

where $3 \le n \le 4$. This should cover all cases in which 'I is some decreasing function of time, up to the limit when 'I is constant.

Note that the above equation (*) is similar to chemical reaction kinetics of many heterogeneous systems

$$\frac{dX}{dt} = nk^n t^{n-1}(1-X)$$
$$X = 1 - \exp(-(kt)^n)$$
$$\ln(\ln\frac{1}{1-X}) = n\ln k + n\ln t$$



Diffusion-controlling Growth (Parabolic growth, x=kt ^{1/2} , and u=kt ^{-1/2} /2)		n (Constant ^v I)	n (Zero ^v I)
	3-D	2.5	1.5
	2-D	2.0	1.0
	1-D	1.5	0.5
Reaction-controlling Growth (Linear growth, x=kt, and u=k)		n (Constant 'I)	n (Zero 'I)
	3-D	4	3
	2-D	3	2
	1-D	2	1

Parabolic Growth

$$x = k\sqrt{t} , u = \frac{dx}{dt} = \frac{k}{2\sqrt{t}} \quad \text{volume of transformed regions} \quad \begin{array}{l} 3 - D : \frac{4\pi}{3} u^{3} t^{3} \\ 2 - D : \pi \delta u^{2} t^{2} \\ 1 - D : \pi \delta^{2} ut \end{array}$$

$$\begin{array}{l} YI \text{ is constant, } u \alpha t^{-1/2} \\ 3 - D \\ \ln(1 - x) = -\frac{4\pi}{3} \int_{0}^{t} v I u^{3} t^{3} dt \\ x = 1 - \exp(-\frac{\pi}{15} v I \cdot k^{3} t^{\frac{5}{2}}) \end{array} \begin{vmatrix} 2 - D \\ \ln(1 - x) = -\pi \delta \int_{0}^{t} v I u^{2} t^{2} dt \\ x = 1 - \exp(-\pi \delta^{v} I \cdot \frac{k^{2}}{8} t^{2}) \end{vmatrix} \begin{vmatrix} 1 - D \\ \ln(1 - x) = -\pi \delta^{2} \int_{0}^{t} v I \cdot u \cdot t dt \\ x = 1 - \exp(-\pi \delta^{2} v I \cdot \frac{k}{3} t^{\frac{3}{2}}) \end{vmatrix}$$

$$\begin{array}{l} vI = 0, u \alpha t^{-1/2}, \text{ number of nuclei=N_{0}} \\ 3 - D \\ \ln(1 - x) = -\frac{4\pi}{3} N_{0} u^{3} t^{3} \\ x = 1 - \exp(-\pi \delta N_{0} u^{2} t^{2} \\ x = 1 - \exp(-\pi \delta N_{0} u^{2} t^{2} \\ x = 1 - \exp(-\pi \delta^{N} N_{0} u^{2} t^{2} \\ x = 1 - \exp(-\pi \delta N_{0} \frac{k^{2}}{4} t) \end{vmatrix}$$

$$\begin{array}{l} 1 - D \\ \ln(1 - x) = -\pi \delta^{2} N_{0} u \cdot t \\ x = 1 - \exp(-\pi \delta^{2} N_{0} \frac{k}{2} \cdot t^{\frac{1}{2}}) \end{aligned}$$

Linear Growth

$$x=kt$$
, $u=\frac{dx}{dt}=k$ volume of transformed region=
 $3-D:\frac{4\pi}{3}u^{3}t^{3}$
 $2-D:\pi\delta u^{2}t^{2}$
 $1-D:\pi\delta^{2}ut$

3-D

$$\ln(1-x) = -\frac{4\pi}{3} \int_{0}^{t^{v}} I u^{3} t^{3} dt \qquad 2-D$$

$$\ln(1-x) = -\pi \delta \int_{0}^{t^{v}} I u^{2} t^{2} dt \qquad \ln(1-x) = -\pi \delta^{2} \int_{0}^{t^{v}} I \cdot u \cdot t dt$$

$$x = 1 - \exp(-\frac{\pi}{3} v I u^{3} t^{4}) \qquad x = 1 - \exp(-\pi \delta^{v} I u^{2} \frac{t^{3}}{3}) \qquad x = 1 - \exp(-\pi \delta^{2} v I \cdot u \frac{t^{2}}{2})$$

$$\begin{array}{c|c} {}^{v}\mathbf{I=0, u=constant, number of nuclei=N_{0}} \\ \hline 3-D \\ ln(1-x) = -\frac{4\pi}{3}N_{0}u^{3}t^{3} \\ x = 1 - exp(-\frac{4\pi}{3}N_{0}u^{3}t^{3}) \end{array} \end{array} \begin{array}{c|c} 2-D \\ ln(1-x) = -\pi\delta N_{0}u^{2}t^{2} \\ x = 1 - exp(-\pi\delta N_{0}u^{2}t^{2}) \end{array} \end{array} \begin{array}{c|c} 1-D \\ ln(1-x) = -\pi\delta^{2}N_{0}u \cdot t \\ x = 1 - exp(-\pi\delta^{2}N_{0}u \cdot t) \end{aligned}$$



Fig. 5.24 (a) Nucleation at a constant rate during the whole transformation. (b) Site saturation—all nucleation occurs at the beginning of transformation. (c) A cellular transformation.

4





Time-Temperature-Transformation (TTT) Curves Continuous Cooling Transformation (CCT) Curves



Cooling Rate required = $\Delta T / \Delta t$ to avoid $\alpha \rightarrow \beta$



Fig.4: Time temperature transformation (schematic) diagram for plain carbon eutectoid steel

At T_1 , incubation period for pearlite= t_2 , Pearlite finish time = t_4

Minimum incubation period t₀ at the nose of the TTT diagram,

M_S=Martensite start temperature M₅₀=temperature for 50% martensite formation M_F= martensite finish temperature



- No energy barrier for decomposition
- Kinetics controlling process
- Spinodal decomposition

(b) Metastable region $\frac{\partial^2 G}{\partial x^2} > 0$

-Small fluctuation, $C \rightarrow A+B$, and $G_C < G_F$, energetically unfavorable -Large fluctuation, $C \rightarrow A+D$ and $G_C > G_E$, energetically favorable -Nucleation and growth



Small compositional fluctuation in the unstable area:

in the stable/meta-stable areas:

$$\frac{\partial^2 G}{\partial X^2} < 0, \quad G_M < G_C, \quad C \to A + B$$
$$\frac{\partial^2 G}{\partial X^2} > 0, \quad G_M > G_C, \quad C \to A + B$$



Phase Separation





Spinodal Decomposition



Spinodal Decomposition

Characteristics of spinodal decomposition

- (1) No energy barrier
- (2) Continuous variation of composition between transformed and untransformed, diffuse interface between transformed and initial phases
- (3) $\triangle H_{mix} > 0 \rightarrow positive deviation (\gamma > 1)$
- (4) Uphill diffusion \rightarrow Negative diffusivity
- (5) Periodic and highly connected of transformed phases
- (6) Systems: Al-Cu, B_2O_3 -Si O_2 glass, CoO-MgO, MgAl₂ O_4 -Al₂ O_3 , etc.

Characteristics of nucleation and growth

- (1) With energy barrier
- (2) Sharp interface
- (3) Random distribution of particle sizes and position in transformed matrix
- (4) Invariance of transformed phase composition with time
- (5) Tendency toward spherical particles

Kinetics of Spinodal Decomposition

(1)J. W. Cahn, Acta. Meta. <u>9</u> (1961), p. 795

- (2)J. W. Cahn, Trans. Met. Soc. AIME, <u>242</u> (1968), p. 166
- (3)J. E. Hillard in "Phase Transformation", ASM (1970), p. 497
- (4) A. K. Jena and M.C. Chaturved, "Phase Transformations", Chap. 9 (1992)

The flux of each constituent in a binary system with a moving lattice, viewed from the edge of sample (stationary coordinate)

$$J_{B} = j_{B} + v_{x}C_{B}; \quad J_{A} = j_{A} + v_{x}C_{A} \qquad v_{x} : \text{velocity of lattice flow}$$

$$J_{net} = J_{A} + J_{B} = j_{A} + j_{B} + v_{x}(C_{A} + C_{B}) = 0$$

$$v_{x} = \frac{-(j_{A} + j_{B})}{(C_{A} + C_{B})} = \frac{1}{(C_{A} + C_{B})}(D_{A}^{I}\frac{\partial C_{A}}{\partial x} + D_{B}^{I}\frac{\partial C_{B}}{\partial x}) = \frac{1}{(C_{A} + C_{B})}(D_{A}^{I} - D_{B}^{I})\frac{\partial C_{A}}{\partial x}$$

$$\therefore J_{B} = j_{B} + \frac{C_{B}}{C_{A} + C_{B}}(D_{A}^{I}\frac{\partial C_{A}}{\partial x} + D_{B}^{I}\frac{\partial C_{B}}{\partial x}) = j_{B} - X_{B}(j_{A} + j_{B}) = -\tilde{D}\frac{\partial C_{B}}{\partial x}$$
where $i_{B} = C_{B}v_{B} = X_{B}C \cdot B_{B}F_{B} = X_{B}C \cdot B_{B}(-\frac{\partial(\mu_{B}/N)}{N})$

where
$$j_B = C_B v_B = X_B C \cdot B_B F_B = X_B C \cdot B_B (-\frac{\partial (\mathcal{P}_B N)}{\partial x})$$

$$j_A = -(1 - X_B)C \cdot B_A(\frac{\partial (\mu_A/N)}{\partial x})$$

v_B: atomic velocity X_{B} : molar fraction $C = C_A + C_B$: #atoms/unit volume B_A, B_B : mobility $\mu\colon$ chemical potential per mole $N = 6 \times 10^{23}$ x: distance

J_i: Flux under stationary coordinate j: Flux under moving coordinate

$$J_{B} = -\tilde{D}\frac{\partial C_{B}}{\partial x} = -(X_{A}D_{B}^{I} + X_{B}D_{A}^{I})\frac{\partial C_{B}}{\partial x}$$
$$j_{B} = -D_{B}^{I}\frac{\partial C_{B}}{\partial x}$$

$$J_{B} = j_{B} - X_{B}(j_{A} + j_{B})$$

$$= \frac{-X_{B}(1 - X_{B})C}{N} \{ [(1 - X_{B})B_{B} + X_{B}B_{A}](\frac{\partial\mu_{B}}{\partial x} - \frac{\partial\mu_{A}}{\partial x}) + (B_{B} - B_{A})[X_{B}\frac{\partial\mu_{B}}{\partial x} + (1 - X_{B})\frac{\partial\mu_{A}}{\partial x}] \}$$

$$X_{B}\frac{\partial\mu_{B}}{\partial x} + (1 - X_{B})\frac{\partial\mu_{A}}{\partial x} = 0 \rightarrow \quad \text{Gibbs-Duhem equation}$$
Hence
$$J_{B} = -\frac{BC}{N} [\frac{\partial(\mu_{B} - \mu_{A})}{\partial x}]$$
where
$$B = X_{B}(1 - X_{B})[(1 - X_{B})B_{B} + X_{B}B_{A}]$$
:the resultant mobility of the binary system
$$\frac{\partial C}{\partial x} = \frac{\partial L}{\partial x} = \frac{BC}{2} (\mu_{A} - \mu_{A})$$

$$\frac{\partial C_{B}}{\partial t} = -\frac{\partial J_{B}}{\partial x} = \left(\frac{BC}{N}\right) \left[\frac{\partial^{2}(\mu_{B} - \mu_{A})}{\partial x^{2}}\right]$$
$$\mu_{B} - \mu_{A} = \overline{G_{B}} - \overline{G_{A}} = \frac{dG}{dX_{B}}$$

G: Gibbs free energy per mole

It is convenient to use free energy per unit volume (f)

$$f = g_{\text{at P=1 atm}} = \frac{GC}{N}$$

f: Helmholtz free energy per unit volume g: Gibbs free energy per unit volume C: Number of atoms per unit volume

$$\mu_{B} - \mu_{A} = \frac{\partial (f^{N}/C)}{\partial X_{B}} = \frac{N}{C} \frac{\partial f}{\partial X_{B}}$$
$$\therefore J_{B} = -\frac{BC}{N} \left[\frac{\partial (\frac{N}{C} \frac{\partial f}{\partial X_{B}})}{\partial x}\right] = -B \frac{\partial}{\partial x} (\frac{\partial f}{\partial X_{B}}) = -B \frac{\partial}{\partial X_{B}} (\frac{\partial f}{\partial X_{B}}) (\frac{\partial X_{B}}{\partial x})$$
$$\therefore J_{B} = -\tilde{D} \frac{\partial C_{B}}{\partial x} = -\tilde{D}C \frac{\partial X_{B}}{\partial x}$$
$$\therefore \tilde{D} = \frac{B}{C} \frac{\partial^{2} f}{\partial X_{B}^{2}} = \frac{B}{N} \frac{\partial^{2} G}{\partial X_{B}^{2}} \qquad (\because f = \frac{GC}{N})$$

within spinodal $\frac{\partial^2 G}{\partial X_B^2} < 0 \Rightarrow \tilde{D} < 0$ Fick's 2nd law $\frac{\partial C_B}{\partial t} = \tilde{D} \frac{\partial^2 C_B}{\partial x^2} = \frac{B}{C} (\frac{\partial^2 f}{\partial X_B^2}) \frac{\partial^2 C_B}{\partial x^2} = \frac{Bf''}{C} \frac{\partial^2 C_B}{\partial x^2}$ General Solution : $C_B - \overline{C}_B = A(\beta, 0) \exp(-\beta^2 (\frac{Bf''}{C})t) \exp(i\beta x)$ $= A(\beta, t) \exp(i\beta x)$ where $\beta = \frac{2\pi}{\lambda}$:wavenumber

$$C(x,t) = \frac{4C_0}{\pi} \sum_{j=0}^{\infty} \frac{1}{(2j+1)} \sin(\frac{(2j+1)\pi x}{h}) \exp(-(\frac{(2j+1)\pi}{h})^2 Dt)$$

$$C(x,0) = \frac{4C_0}{\pi} \sum_{j=0}^{\infty} \frac{1}{(2j+1)} \sin(\frac{(2j+1)\pi x}{h})$$

$$C(x,t) = C(x,0) \exp(-(\frac{(2j+1)\pi}{h})^2 Dt)$$
Amplification Factor (AF) = $\exp(-(\frac{(2j+1)\pi}{h})^2 Dt)$
(1) $D < 0 \Rightarrow \frac{d(AF)}{dt} > 0 \Rightarrow$ Spinodal Decomposition
(2) $D > 0 \Rightarrow \frac{d(AF)}{dt} < 0 \Rightarrow$ Homogenization
$$C(x,t) = \frac{1}{2} \sum_{j=0}^{\infty} \frac{1}{2} \sum_{j=0}^{\infty$$

- λ is the wavelength of the composition modulation
- \overline{c} is the average concentration
- -A(β ,0) is the amplitude of the composition modulation of wave number β at time zero

$$A(\beta,t) = A(\beta,0) \exp(-\beta^2 (\frac{Bf''}{C})t)$$
$$= A(\beta,0) \exp(R(\beta)t)$$

- -A(β ,t) is the amplitude of the Fourier component of wave number β at time t
- -R(β) is an amplification factor

$$R(\beta) = -\beta^2 (\frac{B}{C}) f'$$

f"<0 within spinodal \rightarrow R(β) >0 and the sinusoidal composition modulations are amplified



The amplitude of the composition fluctuation is less at larger wavelength because of the longer diffusion distance, and more at smaller wavelength because of the shorter diffusion distance.



* $\lambda \to 0, \ \beta \to \infty, \ R(\beta) \to \infty$

→ a continuous microstructure should be observed. * However, $\lambda_{measured} \approx 10 \text{ nm}$ is always observed. * Strain energy or interfacial free energy has to be included.

Modified diffusion equations - Effect of composition gradient

- Excess interfacial free energy existing in the diffuse interface between two phases
- The interfacial free energy is positive, which decreases the driving force for spinodal decomposition
- The interfacial free energy increases with decreasing wavelength

Helmholtz free energy of a homogeneous system

 $F = \int f(X_B) dV$

The change in free energy due to the change in concentration of δX_B

$$\delta F = \int \left[\frac{\partial f}{\partial X_B} \delta X_B\right] dV \qquad \text{Note:} \frac{\partial f}{\partial X_B} = \frac{C}{N} \Delta \mu$$

 $f(X_B)$: Helmholtz free energy/unit volume of homogeneous material with a composition X_B . Since the interfacial free energy (γ) is proportional to the square of the composition difference between the coexisting phases across the interface (dX_B / dx)

$$\gamma = k \left(\frac{dX_B}{dx}\right)^2$$

k: gradient energy coefficient

Helmholtz free energy of an inhomogeneous system is

$$F = \int [f(X_B) + \kappa (\frac{dX_B}{dx})^2] dV$$

The change in free energy due to the change in concentration of δX_B

$$\delta F = \int \left[\frac{\partial f}{\partial X_B} \delta X_B + \left(\frac{\partial \kappa}{\partial X_B}\right) \left(\frac{\partial X_B}{\partial x}\right)^2 \delta X_B + 2\kappa \left(\frac{\partial X_B}{\partial x}\right) \delta \left(\frac{\partial X_B}{\partial x}\right)\right] dV$$
$$= \int \left[\frac{\partial f}{\partial X_B} - \left(\frac{\partial \kappa}{\partial X_B}\right) \left(\frac{\partial X_B}{\partial x}\right)^2 - 2\kappa \left(\frac{\partial^2 X_B}{\partial x^2}\right)\right] \delta X_B dV = \int \left[\frac{\partial f}{\partial X_B} - 2\kappa \left(\frac{\partial^2 X_B}{\partial x^2}\right)\right] \delta X_B dV$$

Gibbs free energy of an atom in a concentration gradient is not the same as the Gibbs free energy of that atom in a solution of uniform concentration

$$\gamma = \kappa (\frac{dX_B}{dx})^2$$

Interfacial free energy is proportional to (composition gradient)² **Regular Solution**

(1) In a uniform solution
$$\Delta H_m = \Omega X_A X_B = \Omega X_A (1 - X_A)$$
$$\Omega = Z[E_{AB} - \frac{1}{2}(E_{AA} + E_{BB})] = Z \cdot \Delta E$$
$$\Delta H_m = Z X_A (1 - X_A) \cdot \Delta E = 12C(1 - C) \cdot \Delta E \quad (Z=12)$$
(2) With a concentration predicat

(2) With a concentration gradient



 $\Delta H_{m} = 6C_{o}(1-C_{o})\Delta E$ +3[(C_{o} + \Delta C)(1-(C_{o} + \Delta C))]\Delta E +3[(C_{o} - \Delta C)(1-(C_{o} - \Delta C))]\Delta E =12C_{o}(1-C_{o})\Delta E + 6(\Delta C)^{2}\Delta E =12C_{o}(1-C_{o})\Delta E + 6(\Delta C)^{2}(\Delta x)^{2}\Delta E Uniform concentration Excess Gibbs free energy resulted from

a non-uniform concentration



- (1) At a large wavelength, β is small $\rightarrow \beta^2$ dominates and the amplification factor, R(β) is positive because f" is negative. R(β) tends to approach zero with an increase in wavelength.
- (2) At a small wavelength, β is large $\rightarrow \beta^4$ becomes predominant, and R(β) tends to be negative.



- Note: * When λ is large, decreasing λ means decreasing the diffusion distance $\rightarrow R(\beta)$ increases
 - * When λ is small ($\lambda < \lambda_m$), the gradient energy term is large enough to offset the driving force (f"), then R(β) decreases with decreasing λ .

 \rightarrow Spinodal fluctuation decays \rightarrow Spinodal decomposition will not happen

However, the solid solution can still decompose to its equilibrium state by Nucleation and Growth, but not by the spinodal decomposition.

Effect of coherent strain energy

- Lattice parameter in general varies with composition. Work has to be performed in straining the lattice if the lattice is to remain coherent in the presence of a composition modulation. To maintain the coherence, it will reduce the driving force for phase transformation.
- Coherent strain energy generally is a function of crystallographic direction, which is to determine the morphology of transformed phase.
- -The growth rate will be the maximum in the elastically softest direction.

```
W = Y\delta^2 (Elastic Strain Energy)
Y = \frac{E}{1-t} (Isotropic)
  Y. Stiffness
  E:Young's modulus
   \nu. Poisson's ratio
\delta = \eta (X_B - X_B): disregistry
  X_{R}: Composition
  \overline{X}_{B}: Average composition
f_{strain} = Y\delta^2 = Y\eta^2(X_B - \overline{X_B})^2
        :Coherent strain energy per unit volume
```



$$F = \int [f(X_B) + \eta^2 Y(X_B - \overline{X_B})^2 + k(\frac{dX_B}{dx})^2] dV$$

$$J_B = -B \frac{d}{dx} (\frac{\partial f}{\partial X_B} + 2\eta^2 Y(X_B - \overline{X_B}) - 2k \frac{\partial^2 X_B}{\partial x^2})$$

$$\frac{\partial C_B}{\partial t} = -\frac{\partial J_B}{\partial x} = \frac{B}{C} [(f'' + 2\eta^2 Y) \frac{\partial^2 C_B}{\partial x^2} - 2k \frac{\partial^4 C_B}{\partial x^4})$$

$$R(\beta) = -\frac{B}{C} (f'' + 2\eta^2 Y + 2k\beta^2)\beta^2$$

-Therefore, for an alloy to decompose by spinodal mechanism the $f'' + 2\eta^2 Y$ must be negative as the surface energy term $2k\beta^2$ is always positive Consequently, the boundary corresponding to $f'' + 2\eta^2 Y = 0$ is defined as the coherent spinodal at which $\beta \rightarrow 0, \lambda \rightarrow \infty$ (Ignore the effect of surface energy).

- $2\eta^2 Y$ will be absent at high temperature which is to be relieved by plastic deformation. $2k\beta^2$ is significant only when λ is small ($\lambda \approx 10$ nm).

-To grow, $R(\beta)$ has to be positive. Since β is inherently positive, $R(\beta)$ is positive only if $f'' + 2\eta^2 Y + 2k\beta^2 \le 0$. For a system with spinodal decomposition, κ is expected to be positive. Thus $f'' + 2\eta^2 Y \le 0$. Since Y varies with the direction of crystal, the temp will be maximum for those directions that minimize $2\eta^2 Y$.



 $f'' + 2\eta^2 Y = 0 \rightarrow \beta_C = 0 \Rightarrow$ Coherent Spinodal





- (1) Incoherent miscibility curve (Strain-free) \rightarrow f'=0
- (2) Chemical spinodal curve (Strain-free) $\rightarrow f''=0$
- (3) Coherent miscibility curve

f = free energy change + strain energy →f'=0

(4) Coherent spinodal curve $\rightarrow f''+2 \eta^2 Y=0$







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Fig. 8—The coherent spinodal (dashed line) in Au-Ni where the coherency strain is large and in which elastic moduli vary strongly with composition.²⁵ T_c is the chemical spinodal; T' and T are, respectively, an experimental and theoretical estimate of the coherent spinodal.

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•T>T_N \rightarrow Driving force increases with decreasing temp., $\beta_m \alpha \Delta T$. • T<T_N \rightarrow Mobility decreases with decreasing temp

$$(\frac{2\pi}{\lambda_m})^2 = \beta_m^2 = \frac{(T - T_s^*)S''}{4\kappa} = \frac{(T - T_s)S'' - 2\eta^2 Y}{4\kappa}$$
(1) $\beta_m \uparrow$ when $T \downarrow \rightarrow \lambda_m \downarrow$, $T \downarrow (\Delta T \uparrow)$
(2) $2\eta^2 Y \uparrow \quad \beta_m \downarrow \quad \lambda_m \uparrow$
(3) $\kappa \uparrow \quad \beta_m \downarrow \quad \lambda_m \uparrow$

Q: Is it possible to suppress spinodal decomposition by quenching?

Recall

 $R(\beta_m) = -\frac{B}{2C}(f'' + 2\eta^2 Y)\beta_m^2 \equiv \frac{1}{t}$ $\beta_m = \frac{2\pi}{\lambda}$ and $\tilde{D} = \frac{B}{C}f''$ equivalent to $\frac{1}{t} \alpha \tilde{D}(\frac{1}{\lambda})^2$ $x^2 \approx \tilde{D}t \quad (\lambda = \lambda_m)$ $x = \lambda_m = 10$ nm (measured) $(10^{-6})^2 = 10^{-9} \text{ cm}^2/\text{sec} \cdot t$ $\therefore \tilde{D} = 10^{-9} \text{ cm}^2/\text{sec}$ for solid, $\tilde{D} = 10^{-6} \text{ cm}^2/\text{sec}$ for liquid $t \approx 10^{-3}$ sec for solid,

 $t \approx 10^{-6}$ sec for liquid

→ Transformation time is so short, therefore, it is hard to suppress spinodal decomposition by quenching